

## Lecture 2

## Principal fibre bundles

We will now specialise to principal fibre bundles, so called because the typical fibre is a principally homogeneous space for a lie group. (I realise that I may have just related two things you are unfamiliar with, so let's start with some definitions.)

7. Scholium A **lie group** consists of a manifold  $G$  which is also a group and such that group multiplication  $G \times G \rightarrow G$ ,  $(g, h) \mapsto gh$ , and group inversion  $G \rightarrow G$ ,  $g \mapsto g^{-1}$ , are smooth maps. If  $g \in G$ , we define diffeomorphisms  $L_g: G \rightarrow G$ ,  $h \mapsto gh$ , and  $R_g: G \rightarrow G$ ,  $h \mapsto hg$ , called **left & right multiplication by  $g$** . A vector field  $\xi \in \mathfrak{X}(G)$  is **left-invariant** if  $(L_g)_* \xi = \xi \quad \forall g \in G$ . In other words,  $\xi$  is left-invariant if  $\xi(g) = (L_g)_* \xi(e)$ , with  $e \in G$  the identity. Similarly,  $\xi$  is **right-invariant** if  $(R_g)_* \xi = \xi \quad \forall g \in G$ . The lie bracket of two left-invariant vector fields is left-invariant. The vector space of left-invariant vector fields defines the **lie algebra  $\mathfrak{g}$**  of  $G$ . Since a LIVF is uniquely determined by its value at the identity,  $\mathfrak{g} \cong T_e G$  as a vector space, but we can transport the lie bracket from  $\mathfrak{g}$  to  $T_e G$  in such a way that  $\mathfrak{g} \cong T_e G$  as a lie algebra. We will identify  $\mathfrak{g}$  with  $T_e G$  at times. Under that identification, the maps (as  $g \in G$ )  $(L_g^{-1})_*: T_g G \rightarrow T_e G = \mathfrak{g}$  define a one-form  $\theta$  with values in  $\mathfrak{g}$ , called the **left-invariant Maurer-Cartan one-form**. If  $\xi$  is a LIVF,  $\theta(\xi) = \xi(e)$ . By definition,  $\theta$  is **left-invariant**:  $L_g^* \theta = \theta \quad \forall g \in G$ . It satisfies the **structure equation**  $d\theta = -\frac{1}{2}[\theta, \theta]$  where  $[\theta, \theta]$  is both the  $\wedge$  of one-forms and the lie bracket. In other words,  $d\theta(\xi, \eta) = -[\theta(\xi), \theta(\eta)]$  for vector fields  $\xi, \eta \in \mathfrak{X}(G)$ .

If  $G$  is a matrix lie group,  $\theta_g = g^{-1} dg$  from where left-invariance and the structure equation follows.

Every  $g \in G$  defines a diffeomorphism  $L_g \circ R_{g^{-1}}: G \rightarrow G$ ,  $h \mapsto ghg^{-1}$ . Since  $g e g^{-1} = e$ , its derivative belongs to  $GL(T_e G) = GL(\mathfrak{g})$ . This defines the **adjoint representation** of  $G$  on  $\mathfrak{g}$ :  $Ad_g = (L_g)_* \circ (R_{g^{-1}})_*$

Notice that  $R_g^* \theta = Ad_{g^{-1}} \circ \theta$  (P.T.  $R_g^* \theta_h = \theta_{hg} \circ (R_g)_* = (L_{(hg^{-1})})_* \circ (R_g)_* = (L_{g^{-1}})_* \circ (L_h)_* \circ (R_g)_* = (L_{g^{-1}})_* \circ (R_g)_* \circ (L_h)_* = Ad_{g^{-1}} \circ \theta_h$ )

A **left action** of a lie group  $G$  on a manifold  $M$  is a smooth map  $G \times M \rightarrow M$ , denoted  $(g, a) \mapsto ga$ , satisfying the axioms  $g_1 \cdot (g_2 \cdot a) = (g_1 g_2) \cdot a$  and  $e \cdot a = a \quad \forall a \in M, \forall g_1, g_2 \in G$ . (The last condition follows if  $e$  act via a diffeomorphism.)

Similarly, one defines a **right action**  $M \times G \rightarrow M$ ,  $(a, g) \mapsto a \cdot g$  to be a smooth map such that  $\forall g_1, g_2 \in G$  and  $a \in M$ ,  $(a \cdot g_1) \cdot g_2 = a \cdot (g_1 g_2)$  and  $e \cdot a = a$ . There is no real difference between left and right actions: if  $G$  acts on  $M$  on the right, we can define a left action by  $g \cdot a := a \cdot g^{-1}$  and viceversa. An action of  $G$  on  $M$  is said to be **transitive** if the  $G$ -orbit of any point is all of  $M$ ; equivalently if given any two points in  $M$ , there is some group element taking one to the other. The action is said to be **free** if the only element which fixes any point is the identity. A  **$G$ -torsor** is a manifold  $M$  on which  $G$  acts freely and transitively. It follows that choosing any point in a  $G$ -torsor  $M$  defines a diffeomorphism  $G \cong M$ . So a  $G$ -torsor is like a lie group where we have forgotten the identity. A vector space  $V$  is an abelian lie group and a  $V$ -torsor is just an affine space modelled on  $V$ .  $G$ -torsors are also called **principally homogeneous  $G$ -spaces**.

8. Definition Let  $G$  be a lie group. A **principal  $G$ -bundle** is a fibre bundle  $P \xrightarrow{\pi} M$  together with a smooth right  $G$ -action  $P \times G \rightarrow P$ ,  $(p, g) \mapsto r_g(p) = pg$ , which preserves the fibres ( $\pi(pg) = \pi(p) \quad \forall p \in P, g \in G$ ) and acts freely and transitively on them. It follows that the fibres are the  $G$ -orbits and hence  $M = P/G$ . The condition of local triviality now says that the local trivializations  $\pi^{-1}(U) \xrightarrow{\varphi} U \times G$  are  $G$ -equivariant, where  $\varphi(p) = (\pi(p), \chi(p)) \exists G$ -equivariant smooth map  $\chi: \pi^{-1}(U) \rightarrow G$  which is a fibrewise diffeomorphism. Equivariance means  $\chi(pg) = \chi(p)g$ . A principal  $G$ -bundle  $P \xrightarrow{\pi} M$  is **trivial** if  $\exists$  a  $G$ -equivariant diffeomorphism  $P \xrightarrow{\varphi} M \times G$ .

9. Proposition A principal  $G$ -bundle  $P \xrightarrow{\pi} M$  admits a section if and only if it is trivial.

Proof If  $P \xrightarrow{\pi} M$  is trivial,  $\varphi: P \rightarrow M \times G$ , we define a section  $s: M \rightarrow P$  by  $s(a) = \varphi^{-1}(a, e)$ .

If  $s: M \rightarrow P$  is a section, we define  $\varphi: P \rightarrow M \times G$  by  $\varphi(p) = (\pi(p), \chi(p))$  where  $\chi(p) \in G$  is uniquely determined by  $p = s(\pi(p)) \chi(p)$ . Notice that  $\chi(pg) = \chi(p)g$ , since  $s(\pi(p)) \chi(p)g = s(\pi(pg)) \chi(pg) = pg$ . ■

10. Example Let  $G$  be a Lie group and  $H \subset G$  a closed Lie subgroup. Then  $G \xrightarrow{\pi} G/H$  is a principal  $H$ -bundle. Therefore homogeneous spaces are examples of principal bundles.

Since PFBs are locally trivial, they admit local sections. Let  $\{(U_\alpha, \varphi_\alpha)\}_{\alpha \in A}$  be a trivialising atlas for  $G \rightarrow P \xrightarrow{\pi} M$ . The canonical local sections  $s_\alpha: U_\alpha \rightarrow \pi^{-1}U_\alpha$  are given by  $s_\alpha(a) := \varphi_\alpha^{-1}(a, e)$ . On  $U_{\alpha\beta}$ , we have sections  $s_\alpha$  and  $s_\beta$ . How are they related? Let

$$U_{\alpha\beta} \times G \xleftarrow{\varphi_\beta} \pi^{-1}U_{\alpha\beta} \xrightarrow{\varphi_\alpha} U_{\alpha\beta} \times G \quad \varphi_\alpha(p) = (\pi(p), g_\alpha(p)) \quad g_\alpha: U_\alpha \rightarrow G \text{ s.t. } g_\alpha(p \cdot g) = g_\alpha(p)g$$

Let  $p \in \pi^{-1}U_{\alpha\beta}$ . Then  $(\pi(p), g_\alpha(p)) = \varphi_\alpha(p) = (\varphi_\alpha \circ \varphi_\beta^{-1} \circ \varphi_\beta)(p) = (\varphi_\alpha \circ \varphi_\beta^{-1})(\pi(p), g_\beta(p))$

$$\therefore (\pi(p), \underbrace{g_\alpha(p) g_\beta^{-1}(p)}_{=: \hat{g}_{\alpha\beta}(p)}) = (\varphi_\alpha \circ \varphi_\beta^{-1})(\pi(p), g_\beta(p))$$

Notice that  $\hat{g}_{\alpha\beta}(p \cdot g) = g_\alpha(p \cdot g) g_\beta^{-1}(p \cdot g) = g_\alpha(p) g g^{-1} g_\beta^{-1}(p) = \hat{g}_{\alpha\beta}(p)$ , so it's constant on the fibres and hence

$$\hat{g}_{\alpha\beta} = \pi^* g_{\alpha\beta} \quad \exists g_{\alpha\beta}: U_{\alpha\beta} \rightarrow G \quad \text{and} \quad (\varphi_\alpha \circ \varphi_\beta^{-1})(a, g) = (a, g_{\alpha\beta}(a)g)$$

It follows that  $\{g_{\alpha\beta}: U_{\alpha\beta} \rightarrow G\}$  obeys the cocycle conditions. Then  $\{L \circ g_{\alpha\beta}: U_{\alpha\beta} \rightarrow \text{Diff}(G)\}$  are the transition functions of the PFB; although one often refers to  $\{g_{\alpha\beta}\}$  as the transition functions.

Finally we can answer the question: how are the canonical local sections related on overlaps?

Notice that  $g_\alpha \circ s_\alpha$  is the constant map  $U_\alpha \rightarrow G$  sending  $a \mapsto e \quad \forall a \in U_\alpha$ . Then,  $g_\alpha(p) = g_{\alpha\beta}(\pi(p)) g_\beta(p)$ , hence for  $p = s_\beta(a)$ ,  $g_\alpha(s_\beta(a)) = g_{\alpha\beta}(a) = g_\alpha(s_\alpha(a)) g_{\alpha\beta}(a) = g_\alpha(s_\alpha(a)) g_{\alpha\beta}(a)$

Since  $g_\alpha$  is a diffeomorphism,  $s_\beta(a) = s_\alpha(a) g_{\alpha\beta}(a) \quad \forall a \in U_{\alpha\beta}$ .